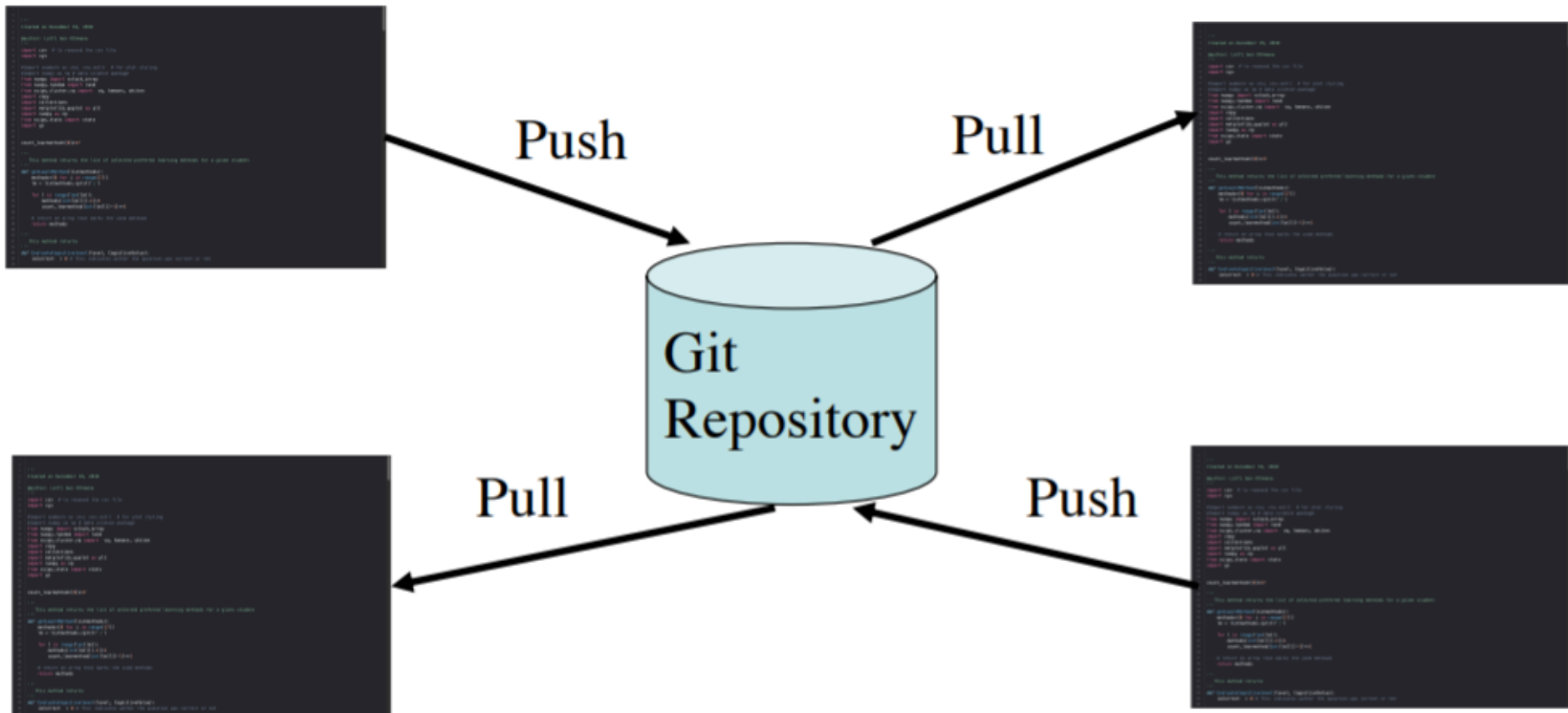


# Concurrency Viewpoint

Lotfi ben Othmane

# Client-Server Architecture



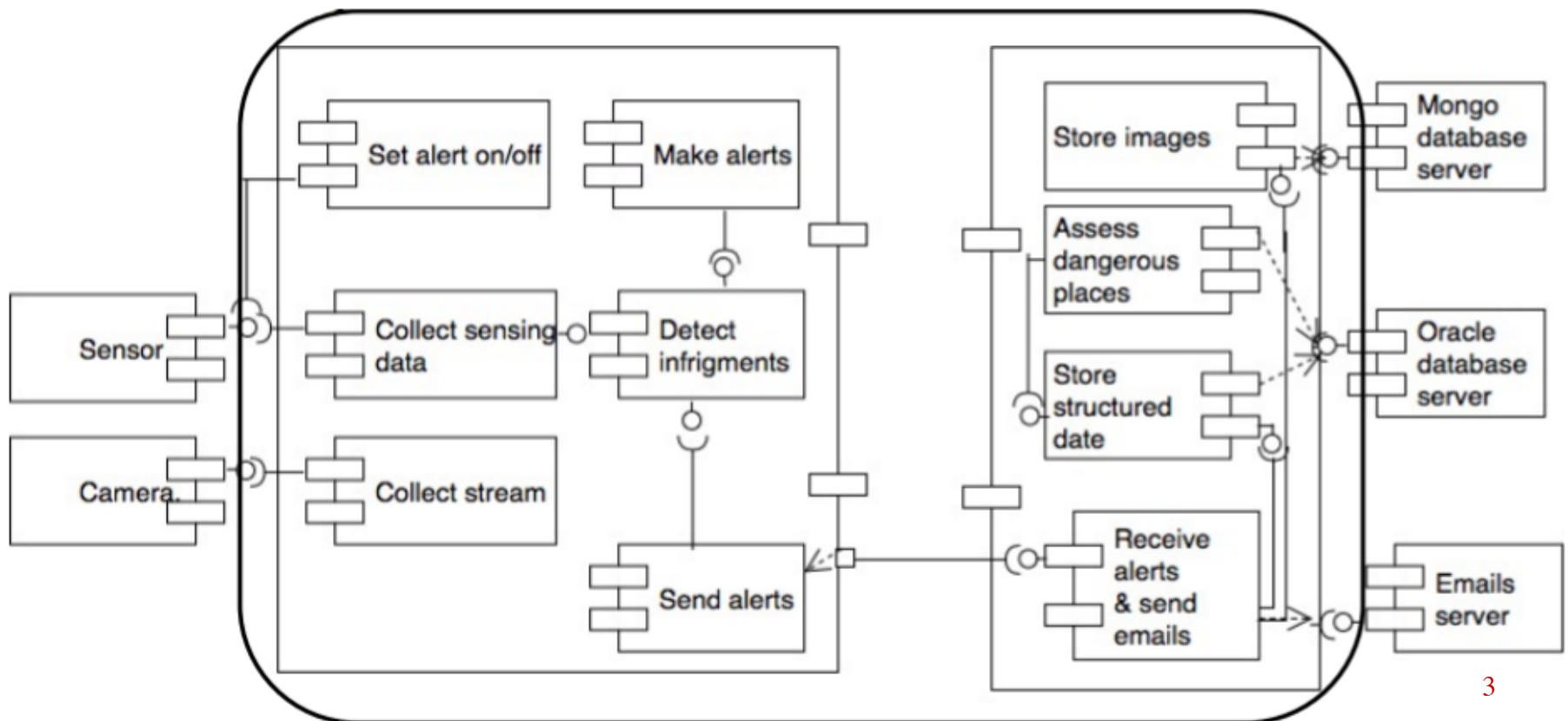
We deploy only one application server.  
Each user can install the client on their device.

# Motivating Example (1)

How many processes **should** the software run in at **most**?

How many processes **should** the software run in the **least**?

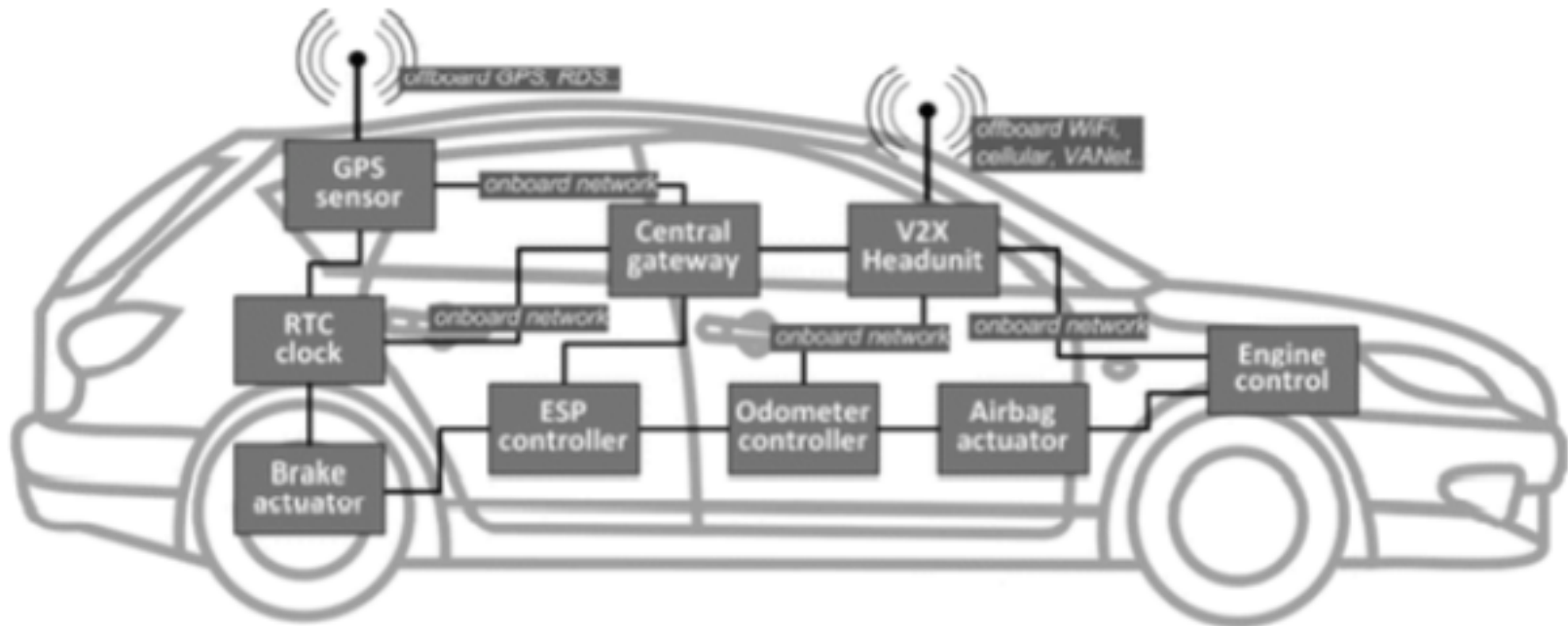
How many processes **should** the software run in?



# Motivating Example (2)

How many processes run in the car?

How do they communicate?



# Motivating Example (2)

```
import can
```

```
PID_REQUEST = 0x7DF
```

```
PID_RESPONSE = 0x7E8
```

What happen when there are data in the CAN bus but the program is busy processing previously received data?

```
bus = can.interface.BUS(channel='can0', bustype='socketcan_native')
```

```
Message = can.Message(arbitration_id=PID_REQUEST, data=[ID_FIRST_BYTE, ID_SECOND_BYTE, pid, 0x00, 0x00, 0x00, 0x00, 0x00], extended_id=False)
```

```
bus.send(message)
```

```
message = bus.recv()
```

```
    if message.arbitration_id == PID_RESPONSE:
```

# Overview

Concurrency viewpoints involve partitioning the system into components that execute at the same time and setting coordination and control mechanisms for these components.

# Overview

Concurrency viewpoint includes:

**Process model** – the set of processes and threads and inter-process communication mechanisms

**State model** – the set of states and transitions for some functional elements

# Concurrency vs Parallelism

**Parallelism**: operations are performed on **independent** or **duplicated** resources. The results may be merged.

**Concurrency**: operations are performed on **shared** resources considering a set of constraints.



# Motivating Example

```
import can
```

```
PID_REQUEST = 0x7DF
```

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PID_RESPONSE = 0x7E8
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bus = can.interface.BUS(channel='can0', bustype='socketcan_native')
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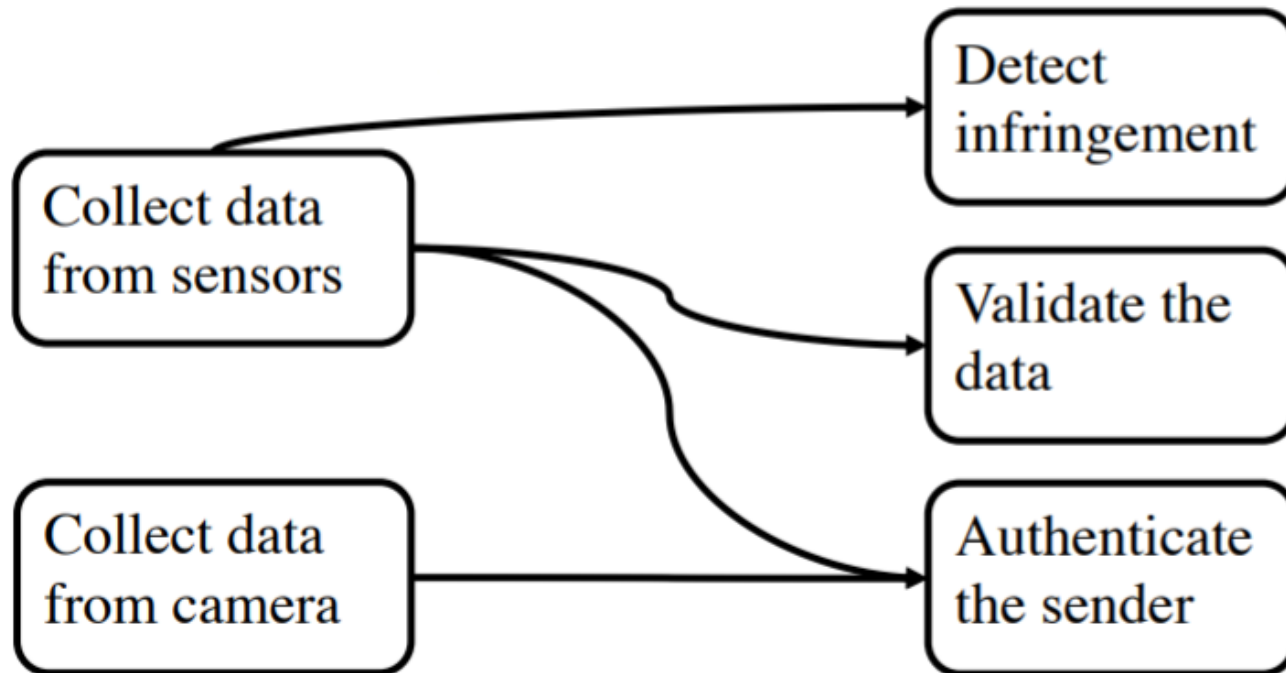
Use threading to solve the problem of data loss

# Requirements Types Related to Concurrency

1. Availability – through redundancy
2. Modifiability – better flexibility to extend the system
3. Scalability – support heavy load
4. Security – rights to access resources
5. Performance – we will revisit this

# Principle: Balance Computation and Communication

1. Should we have “validate the data” in a separate process? **How do you partition the functionalities into processes?**
2. Should we have “collect data from sensors” and “collect data from cameras” in the same process? **What is the cost of communication?**



# Concerns 1 – Task Structure

Define the system process structure (set of processes) considering:

- Partitioning the workload into the processes
- Use operating system capabilities in terms of process grouping and threading

# Concerns 1 – Task Structure

Concurrency elements:

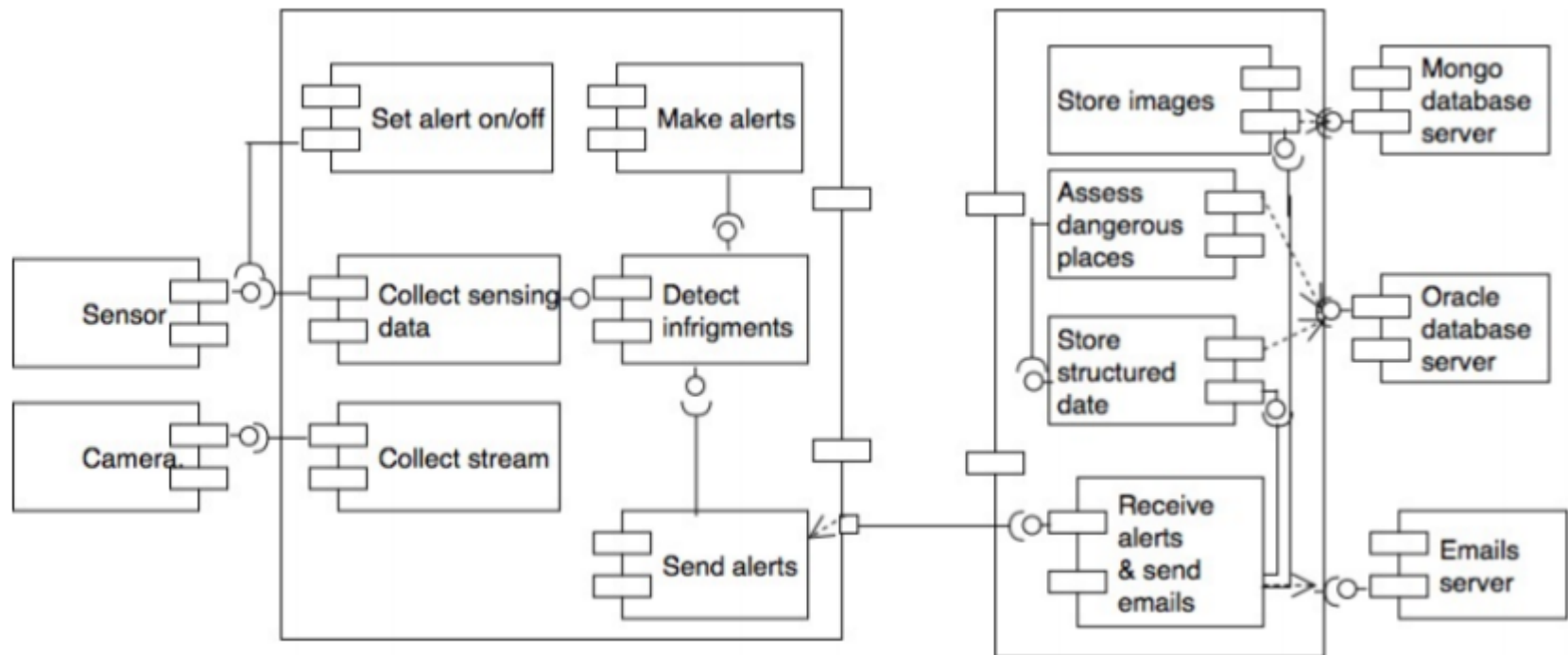
**Process** – independent isolated execution unit, each uses an OS execution environment.

**Thread** – execution unit that can be scheduled within processes.

**Process group** – a set of processes that address a concern.

# Concerns 1 – Task Structure

How many processes do we need?



# Concerns 2 – Map Functional Elements to Processes

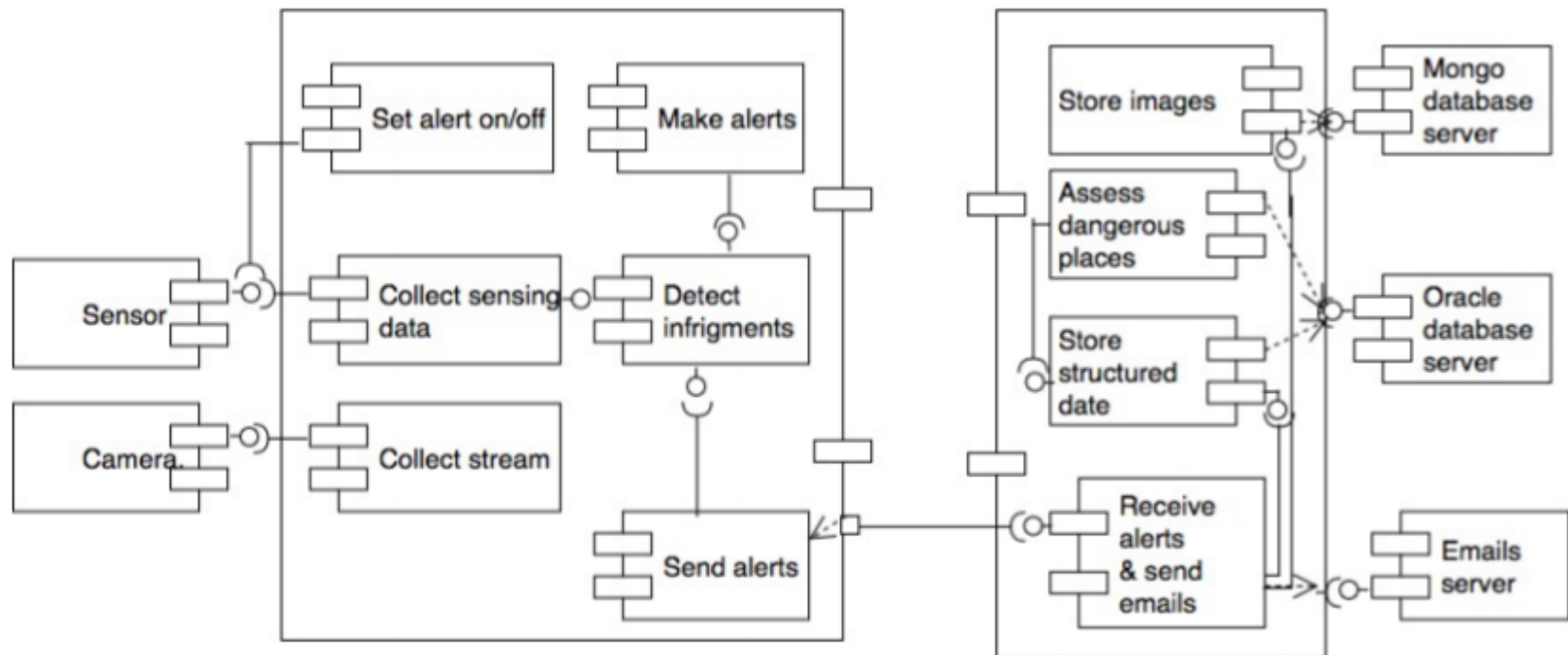
Goal: Map functional elements to tasks

Questions:

1. Which functional elements need to be isolated from each other?
2. Which functional elements need to cooperate closely?

# Concern 2 – Map Functional Elements to Processes

- Should we make detect infringements, send alerts, and make alerts in one process or separate processes?
- What about collect sensing data and collect camera stream?





# Concern 3 – Inter-process Communication

1. Message passing – send and receive messages through the network
2. Remote procedure calls – a process calls a procedure on another process
3. Application Programming Interface (API), e.g. web services and microservices
4. Data-sharing mechanisms – shared memory, files, and databases
5. Coordination mechanisms – e.g. semaphore and mutex
6. Etc.

# Concern 3 – Inter-process Communication

```
import can
```

```
PID_REQUEST = 0x7DF
```

```
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```

```
bus = can.interface.BUS(channel='can0', bustype='socketcan_native')
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```

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bus.send(message)
```

```
message = bus.recv()
```

```
    if message.arbitration_id == PID_RESPONSE:
```

What mechanism is used to  
communicate with the car?

# Concern 3 – Inter-process Communication

```
import java.rmi.*;
import java.rmi.server.*;
public class AdderRemote extends UnicastRemoteObject implements Adder{
AdderRemote()throws RemoteException{
super();
}
public int add(int x,int y){return x+y;}
}
```

```
import java.rmi.*;
public class MyClient{
public static void main(String args[]){
try{
Adder stub=(Adder)Naming.lookup("rmi://localhost:5000/sonoo");
System.out.println(stub.add(34,4));
}catch(Exception e){}
}
}
```

# Concern 3 – Inter-process Communication

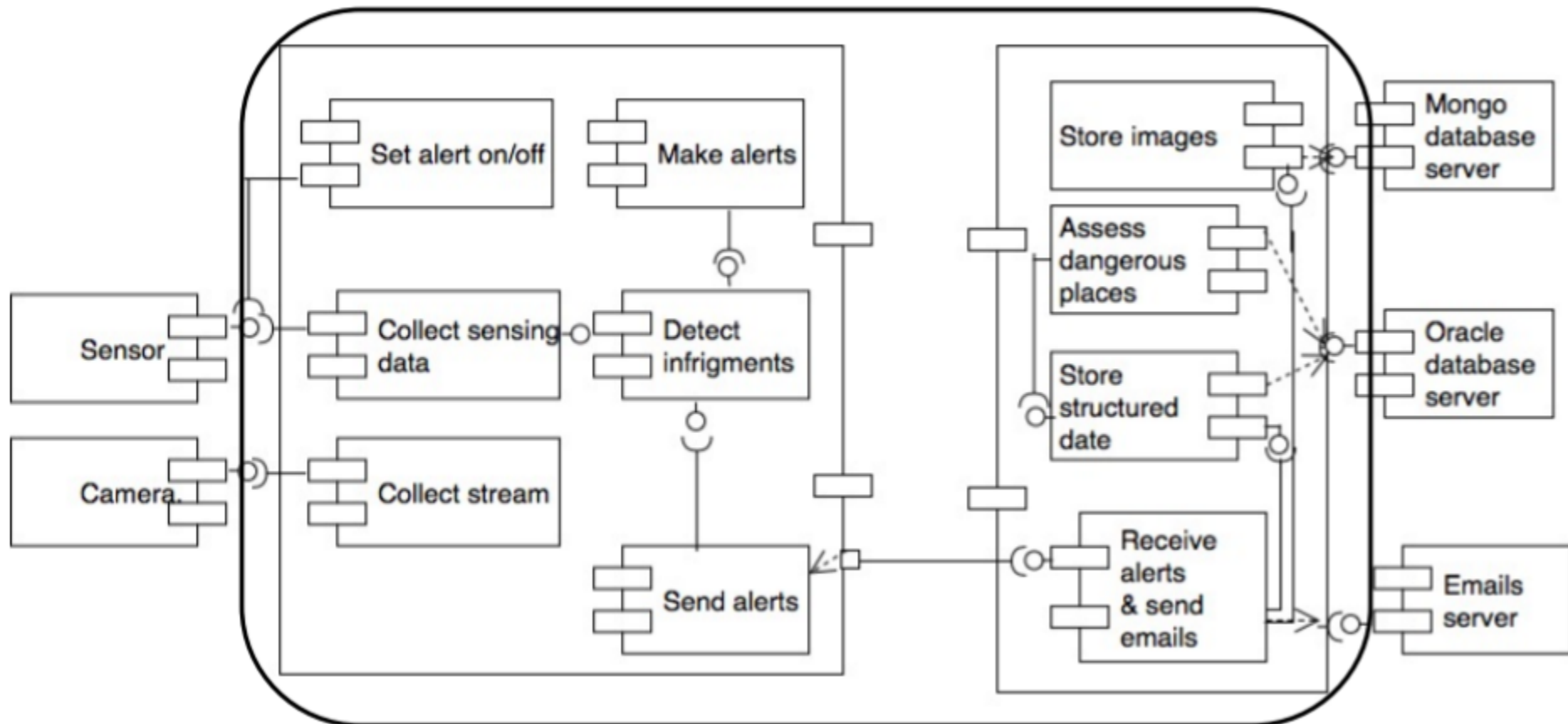
Each inter-process communication mechanism has advantages and disadvantages

Criteria:

1. Synchronous vs asynchronous communication
2. Type of data (Jason, xml)
3. Persistence
4. Location of the communicating process (same node?)
5. Performance – use of transient object provides better performance than use of persistent object
6. Reliability – loss of messages, failure of process
7. Etc.

# Concern 3 – Inter-process Communication (IPC)

What mechanism should you use for sensor data collection communication?



# Concern 4 – State Management

The runtime state of some system elements is important to correct operation of the system.

- In event-driven systems

The elements would have

- A set of states
- A set of transitions between the states



# Concern 4 – State Management

```
import can
```

```
PID_REQUEST = 0x7DF
```

```
PID_RESPONSE = 0x7E8
```

Would it be ok that two nodes send on the bus at the same time?

```
bus = can.interface.BUS(channel='can0', bustype='socketcan_native')
```

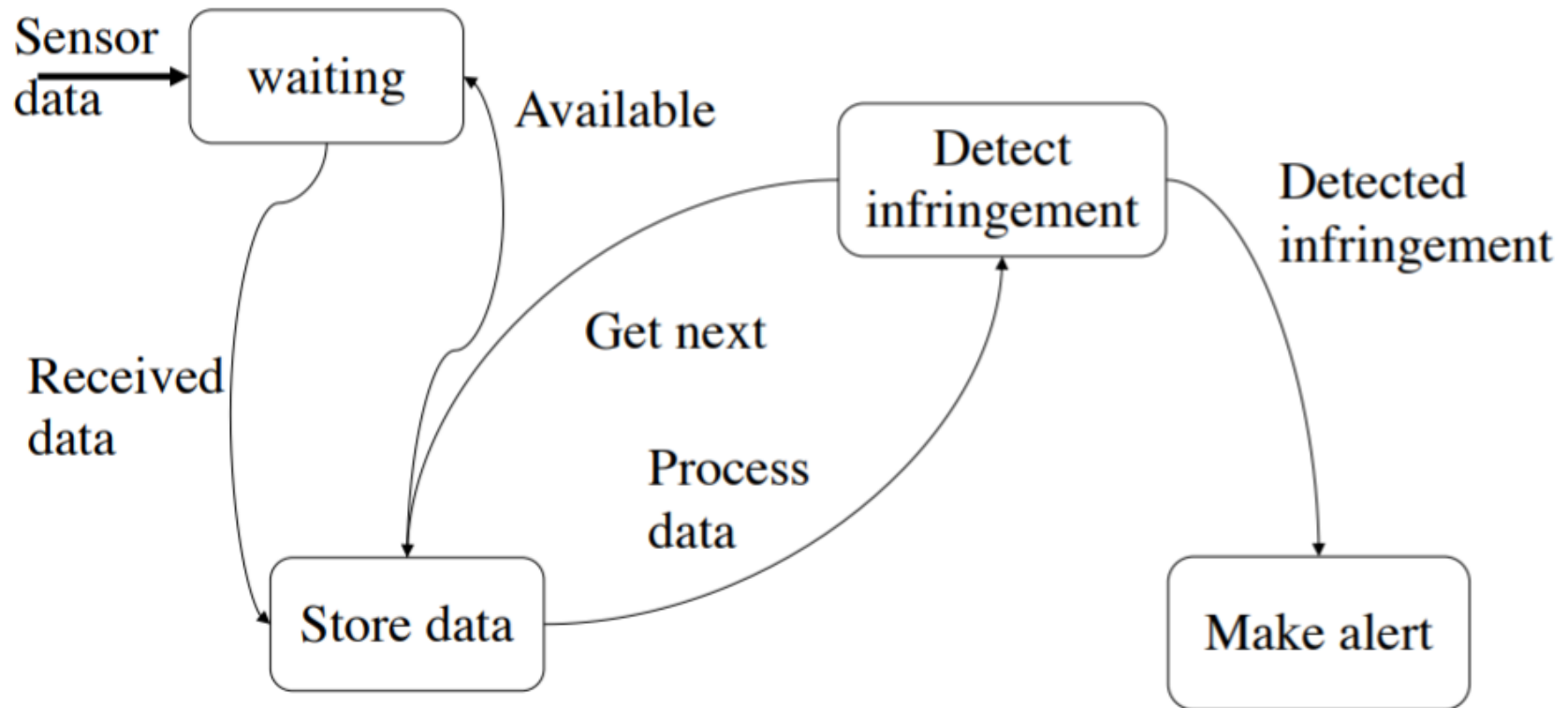
```
Message = can.Message(arbitration_id=PID_REQUEST, data=[ID_FIRST_BYTE, ID_SECOND_BYTE, pid, 0x00, 0x00, 0x00, 0x00, 0x00], extended_id=False)
```

```
bus.send(message)
```

```
message = bus.recv()
```

```
    if message.arbitration_id == PID_RESPONSE:
```

# Concern 4 – State Management





# Concern 5 – Synchronization and Integrity

- Data shared among a set of threads/processes must be coherent and not corrupt.
- Concurrency mechanisms need to coordinate concurrent activities on shared resources.

# Concern 6 – Support for Scalability

Concurrency allows to scale systems to address heavy load.

Little concurrency or naïve synchronization mechanisms negatively impact the ability to scale the system

- Functionalities that can run in parallel
- Constraint: the shared resources

# Concern 7 – Startup and Shutdown

- Processes may have dependencies.
- Starting the system set of processes should consider these dependencies
- Shutting down the system needs to consider the processes' dependencies – e.g. ensure no data is lost

# Concern 8 – Task Failure

- Some of the system's processes could fail, e.g. due to hardware failure or exception.
- Concurrency design should include system-wide monitoring and recovery in case of failure.

# Concern 9 - Reentrancy

- Component A needs to correctly operate though it is used by a set of concurrent components  $B_i$ .
- E.g. the data analytics component needs to be reentrant to allow data storage queries.

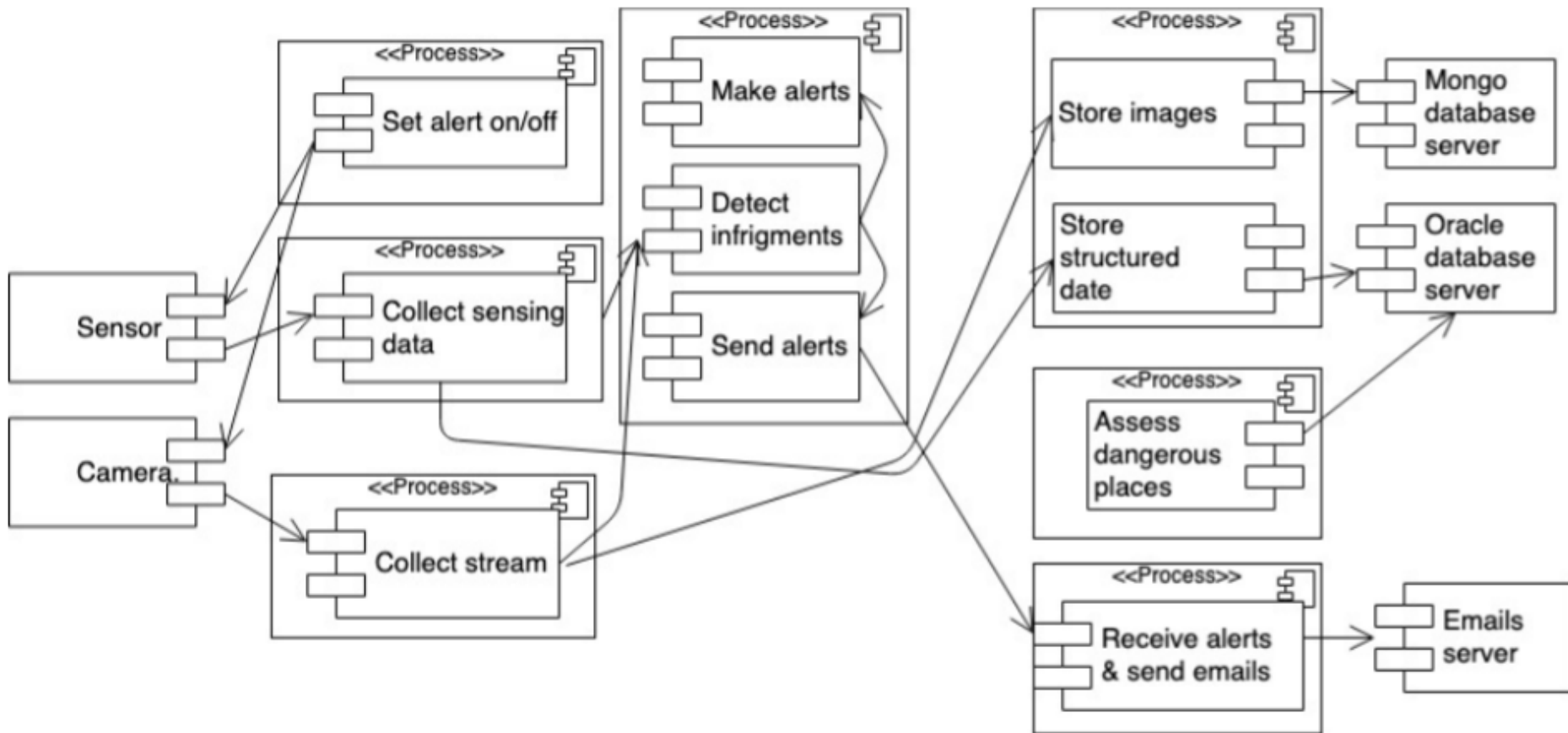
# Concurrency Model

Concurrency view maps functional elements to runtime execution entities via concurrency model.

Concurrency model includes:

1. Processes
2. Process groups
3. Threads
4. Inter-process communication

# Example - Representation of Concurrency



# Activities for Concurrency Model

1. Map elements to processes – define the number of needed processes and assign functional elements to processes.
2. Determine threading design – number of threads for each process.
3. Determine mechanisms for resource sharing – identify shared resources and protocols to use them.
4. Determine the IPC (inter-process communication) mechanisms – decide on IPC for each communicating process.
5. Analyze contention – checks for processes that require shared resources concurrently.
6. Analyze deadlocks – check if Process A waits for a resource used by process B and B waits for A for another resource.



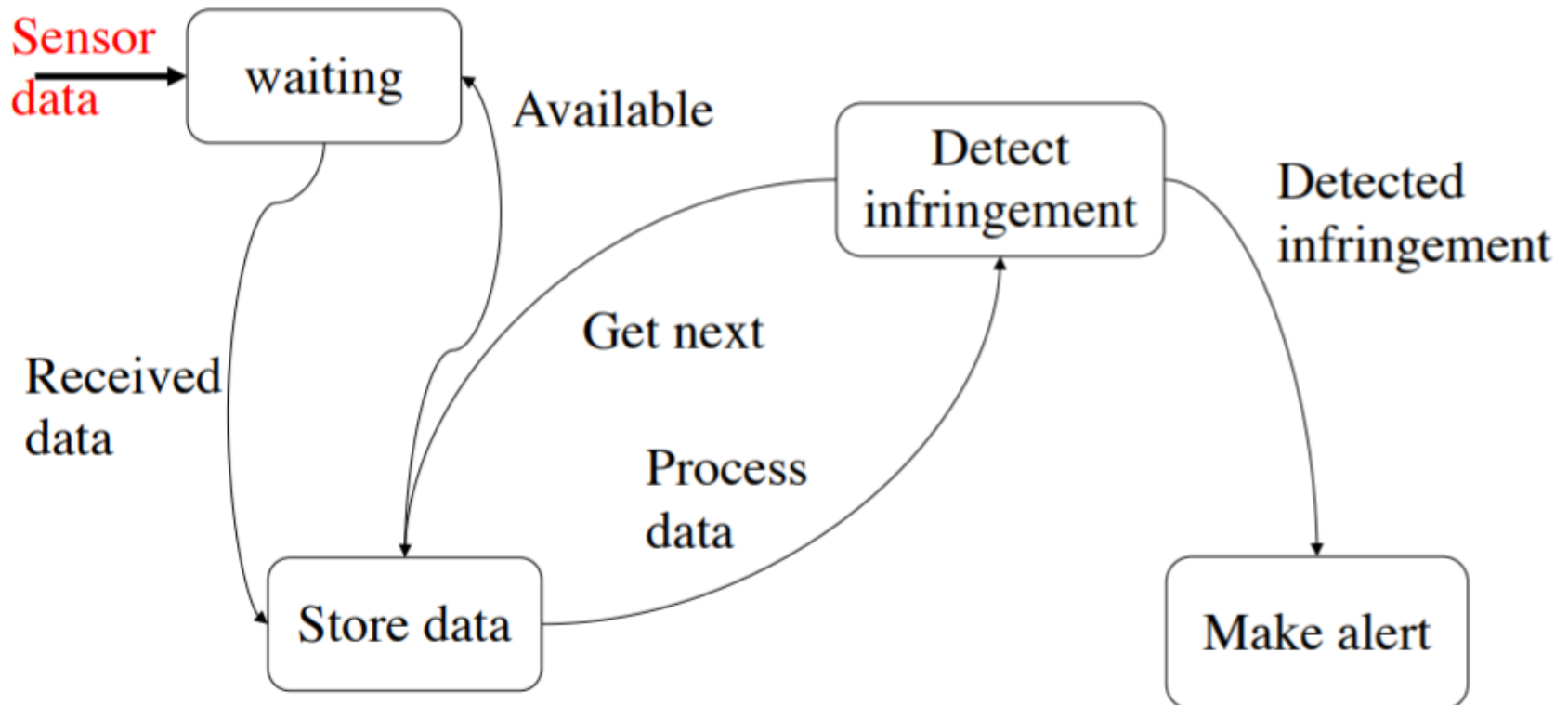
# State Models

A state model describes the set of states that system runtime elements can be in and valid transition between them.

Entities:

- State – condition of the element
- Event – something of interest has happened
- Transition – change of state due to event
- Action – piece of processing associated with transaction

# State Models



# Self-Check

1. What are the two models that are used to represent concurrency?
2. Is concurrency model a UML diagram?
3. What factors would you use to allocate functionalities to processes?

Thank You